# Robotics, MS

For program contact information, please visit this website (https://coe.northeastern.edu/academic-programs/ms-robo/).

The multidisciplinary Master of Science program in robotics is offered by the College of Engineering and the Khoury College of Computer Sciences. The program is designed to provide students comprehensive training in algorithms, sensors, control systems, and mechanisms used in robotics.

In this degree program, students will be admitted (as of Spring 2025) to the college associated with their concentration, and their degree is awarded by that college. The concentrations are associated with the colleges as follows:

- · Computer Science-Khoury College of Computer Sciences
- · Electrical and Computer Engineering—College of Engineering
- · Mechanical Engineering—College of Engineering

Students will follow all policies associated with their home college.

## **Gordon Institute of Engineering Leadership**

Master's Degree in Robotics with Graduate Certificate in Engineering Leadership

Students may complete a Master of Science in Robotics in addition to earning a Graduate Certificate in Engineering Leadership (https://catalog.northeastern.edu/graduate/engineering/multidisciplinary/engineering-leadership-graduate-certificate/). Students must apply and be admitted to the Gordon Engineering Leadership Program in order to pursue this option. The program requires fulfillment of the 16-semester-hour curriculum required to earn the Graduate Certificate in Engineering Leadership, which includes an industry-based challenge project with multiple mentors. The integrated 40-semester-hour degree and certificate will require 24 semester hours of advisor-approved robotics technical courses.

# **Program Requirements**

Complete all courses and requirements listed below unless otherwise indicated.

### **Core Requirements**

| Code                                | Title   | Hours |
|-------------------------------------|---|-------|
| Mechanical Engineering              |   |       |
| Complete one of the following:      |   | 4     |
| ME 5250                             | Robot Mechanics and Control                           |       |
| ME 5659                             | Control Systems Engineering                           |       |
| Electrical and Computer Engineering |   |       |
| Complete one of the following:      |   | 4     |
| EECE 5550                           | Mobile Robotics                                       |       |
| EECE 5552                           | Assistive Robotics                                    |       |
| EECE 5554                           | Robotics Sensing and Navigation                       |       |
| Computer Science                    |   |       |
| Complete one of the following:      |   | 4     |
| CS 5180                             | Reinforcement Learning and Sequential Decision Making |       |
| CS 5335                             | Robotic Science and Systems                           |       |

#### **Concentrations**

Complete one of the following concentrations:

- Computer Science (p. 2)—Khoury College of Computer Sciences
- Electrical and Computer Engineering (p. 2)—College of Engineering
- · Mechanical Engineering (p. 2)-College of Engineering

## **Program Credit/GPA Requirements**

32 total semester hours required Minimum 3.000 GPA required

# 2 Robotics, MS

ME 7945

| 2       | Robotics, MS                           |  |       |
|---------|--|--|-------|
| COMPL   | JTER SCIENCE                           |  |       |
| Code    |  | Title  | Hours |
| Studer  | nts in the computer science concentra  | ation follow the Khoury College of Computer Sciences co-op policies.   |       |
| Requir  | ed Course                              |  |       |
| Compl   | ete one additional CS course not used  | to fulfill the core requirements:  | 4     |
|         | 5180                                   | Reinforcement Learning and Sequential Decision Making  |       |
| CS      | 5335                                   | Robotic Science and Systems  |       |
| Compl   | ete one of the following options:      | •  |       |
|         | ework Option                           |  |       |
|         | ete 16 semester hours of courses from  | n the elective course list. (p. 3)   | 16    |
| Project | t Option                               | * '  |       |
| CS 867  |  | Master's Project   | 4     |
| Compl   | ete 12 semester hours of courses from  |  | 12    |
| Thesis  |  | ·  |       |
| CS 867  | ·                                      | Master's Project   | 4     |
| CS 799  |  | Thesis   | 4     |
|         | ete 8 semester hours of courses from   |  | . 8   |
| July    | 222 2 3020102010 01 0001000 110111     |  | O .   |
| ELECTI  | RICAL AND COMPUTER ENGINEERING         |  |       |
| Code    |  | Title  | Hours |
| Studer  | nts in the electrical and computer eng | ineering concentration follow the College of Engineering co-op policies.   |       |
| -       | ed Course                              |  |       |
| Compl   | ete one additional EECE course not us  | sed to fulfill the core requirements:  | 4     |
| EEC     | E 5550                                 | Mobile Robotics  |       |
| EEC     | E 5552                                 | Assistive Robotics   |       |
| EEC     | E 5554                                 | Robotics Sensing and Navigation  |       |
| Compl   | ete one of the following options:      |  |       |
| Course  | work Option                            |  |       |
| Compl   | ete 16 semester hours of courses from  | m the elective course list. (p. 3)   | 16    |
| Project | t Option                               |  |       |
| EECE 7  | 7945                                   | Master's Project   | 4     |
| Compl   | ete 12 semester hours of courses from  | n the elective course list. (p. 3)   | 12    |
| Thesis  | Option                                 |  |       |
| EECE 7  | 7945                                   | Master's Project   | 4     |
| EECE 7  | 7990                                   | Thesis   | 4     |
| Compl   | ete 8 semester hours of courses from   | the elective course list. (p. 3)   | 8     |
|         | ng Committee and Graduate School o     | students must successfully complete the thesis submission process, including f Engineering signatures and submission of an electronic copy of their MS Thesis to |       |
| MECHA   | ANICAL ENGINEERING                     |  |       |
| Code    |  | Title  | Hours |
| Studer  | nts in the mechanical engineering con  | centration follow the College of Engineering co-op policies.   |       |
| Requir  | ed Course                              |  |       |
| Compl   | ete one additional ME course not use   | d to fulfill the core requirements:  | 4     |
| ME      | 5250                                   | Robot Mechanics and Control  |       |
| ME      | 5659                                   | Control Systems Engineering  |       |
| Compl   | ete one of the following options:      |  |       |
| Course  | work Option                            |  |       |
| Compl   | ete 16 semester hours of courses from  | n the elective course list. (p. 3)   | 16    |
|         | t Option                               |  |       |
| ME 79   |  | Master's Project   | 4     |
| Compl   | ete 12 semester hours of courses from  |  | 12    |
| Thesis  |  |  |       |
| 145.30  | 45                                     | Markada Buda A   |       |

4

Master's Project

ME 7990 Thesis 4
Complete 8 semester hours of courses from the elective course list. (p. 3) 8

In addition to completing the thesis course, students must successfully complete the thesis submission process, including securing Committee and Graduate School of Engineering signatures and submission of an electronic copy of their MS Thesis to ProQuest.

# **Elective Course List**

Any course in the following list will serve as an elective course, provided the student satisfies prerequisites.

| Code      | Title  | Hours |
|-----------|--|-------|
| CS 5097   | Mixed Reality  |       |
| CS 5100   | Foundations of Artificial Intelligence   |       |
| CS 5170   | Artificial Intelligence for Human-Computer Interaction                         |       |
| CS 5330   | Pattern Recognition and Computer Vision  |       |
| CS 5340   | Computer/Human Interaction   |       |
| CS 5800   | Algorithms   |       |
| CS 6120   | Natural Language Processing  |       |
| CS 6140   | Machine Learning   |       |
| CS 6350   | Empirical Research Methods   |       |
| CS 7140   | Advanced Machine Learning  |       |
| CS 7150   | Deep Learning  |       |
| CS 7180   | Special Topics in Artificial Intelligence                                      |       |
| EECE 5550 | Mobile Robotics  |       |
| EECE 5552 | Assistive Robotics   |       |
| EECE 5554 | Robotics Sensing and Navigation  |       |
| EECE 5580 | Classical Control Systems  |       |
| EECE 5639 | Computer Vision  |       |
| EECE 5642 | Data Visualization   |       |
| EECE 5644 | Introduction to Machine Learning and Pattern Recognition                       |       |
| EECE 7150 | Autonomous Field Robotics  |       |
| EECE 7323 | Numerical Optimization Methods   |       |
| EECE 7337 | Information Theory   |       |
| EECE 7370 | Advanced Computer Vision   |       |
| EECE 7397 | Advanced Machine Learning  |       |
| EECE 7398 | Advanced Special Topics in Electrical and Computer Engineering (Legged Robots) |       |
| IE 6500   | Human Performance  |       |
| IE 7280   | Statistical Methods in Engineering   |       |
| IE 7315   | Human Factors Engineering  |       |
| IE 7615   | Neural Networks and Deep Learning  |       |
| ME 5240   | Computer Aided Design and Manufacturing  |       |
| ME 5245   | Mechatronic Systems  |       |
| ME 5250   | Robot Mechanics and Control  |       |
| ME 5654   | Elasticity and Plasticity  |       |
| ME 5655   | Dynamics and Mechanical Vibration  |       |
| ME 5659   | Control Systems Engineering  |       |
| ME 5665   | Musculoskeletal Biomechanics   |       |
| ME 6200   | Mathematical Methods for Mechanical Engineers 1                                |       |
| ME 6260   | Introduction to Microelectromechanical Systems (MEMS)                          |       |
| ME 6250   | Wearable Robotics  |       |
| ME 7247   | Advanced Control Engineering   |       |
| PT 5170   | Motor Control  |       |
| PT 5321   | Applications of Biomechanics in Human Function and Movement                    |       |
| PT 7005   | Experimental Design and Applied Statistics                                     |       |
| PT 7020   | Technologies in Movement and Rehabilitation Science                            |       |
|           |  |       |